

#### Marine Services

# Installation and maintenance... for every ocean



# Innovation

# Oil & Gas

Alcatel-Lucent Submarine Networks own and operate state-of-the-art vessels, including remote operated vehicle spreads to operate in the Oil & Gas and renewable energy markets.

# **Deep Science**

Alcatel-Lucent Submarine Networks develop technologies and install Deep Science, making power and fibre optics available on the seafloor for the Oil & Gas and Science communities. Tailored service agreements to meet individual system owners' needs, based on:

- DMOQs
- Service scope
- System complexity
- Response time

#### Worldwide organisation with a large pool of operational resources:

- High performance vessels and ROVs
- Highly qualified personnel
- Wet plant spares storage on board or in depot
- Spares management
- Cable awareness for seabed users
- Dispersion management
- In-service repairs
- Post-repair burial
- Post-repair reporting and charting
- Periodic inspection and cable protection services

#### Cable jointing:

- All major jointing technologies
- Guaranteed supply of spares and piece-parts
- Full member of UJ Consortium
- Provision of UJ common components
- Provision of UJ kits and specific end kits for all UJ qualified cables





# Marine Maintenance Expertise and innovation





#### Complete all-inclusive service

- Deepwater repairs
- Shallow water repairs
- Pro-active maintenance
- 24/7/365 operations
- Worldwide coverage





#### lle de Brehat, lle de Sein, lle de Batz





# Ile de Brehat / Ile de Sein / Ile de Batz

#### Technical Specifications

DESCRIPTION / POSITIONING	Three state-of-the-art vessels, highly powerful for long-haul cable installation and burying
	in the harshest conditions. Duplex DP and Integrated Control System
OWNER	ALDA MARINE
OPERATOR	ALDA MARINE S.A.S.
SHIP MANAGER	LOUIS DREYFUS ARMATEURS S.A.S.
FLAG	French
CONSTRUCTION YEAR	2002
LENGTH OVERALL	140.36 m
BREADTH	23.40 m
DRAFT	8.00 m (summer draft)
DEADWEIGHT	9820 mt
ACCOMMODATION	Single cabins: 60; double cabins: 5
CABLE TANK CAPACITY	Main cable tank: 2 x 2500 tonnes (max cap each tank: 3500 tonnes), 2 x 1500 m³
	Spare cable tank: 2 x 250 tonnes, 2 x 150 m <sup>3</sup>
REPEATER STORAGE	2 × 100
CABLE MACHINERY	1 Linear Cable Engine – DOWTY 21 Wheel pairs, Drum Engine – DOWTY 6T DOHB / 28T Drum,
	2 Transporter – DOWTY 2 Wheel Pairs, 1 Stern Hauler – DOWTY 2 Wheel Pairs
TYPE OF PLOUGH	1 SMD HD3 Plough – burial in all soils (including fractured rocks). Max burial: 3,00 m
CABLE LAYING SOFTWARE	MakaiLay
DYNAMIC POSITIONING	DP2 BV PDY MATAR ALSTOM
TRANSIT SPEED	15 knots
BOLLARD PULL	100 tonnes
POWER GENERATION	4 x 4320 kW MAK + 1 x 1360 kW MAK
THRUSTERS	2 x Lips 1500 kW Bow Thrusters, 1 x Lips 720 rpm - 1500 kW AZ Fore Thruster
	2 x Lips 1500 kW Aft Thrusters
PROPULSION	2 electrically driven fixed pitch propellers. Output 4000 kW each. Propeller diameter: 3700 mm
	Max propeller speed: 146 rpm



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### lle de Ré



# lle de Ré

#### **Technical Specifications**

DESCRIPTION / POSITIONING	High-speed cable maintenance vessel, ideal for work in harsh conditions.
	Dynamic Positioning and Integrated Control System
OWNER	ALDA MARINE MAINTENANCE ILE DE RE S.A.S.
OPERATOR	ALDA MARINE S.A.S.
SHIP MANAGER	LOUIS DREYFUS ARMATEURS S.A.S.
FLAG	French
CONSTRUCTION YEAR	1982
CONVERSION YEAR	2002
LENGTH OVERALL	143.40 m
BREADTH	23.30 m
DRAFT	7.22 m (summer draft)
DEADWEIGHT	5378 mt
ACCOMMODATION	Single cabins: 40; double cabins: 10
CABLE TANK CAPACITY	2 x 1500 tonnes / 910 m³ + 1 x 1100 tonnes / 680 m³ + 2 x 350 tonnes / 195 m³ + 1 x 240 tonnes / 142 m³
REPEATER STORAGE	2 × 20
CABLE MACHINERY	Drum Cable Engine – 2 x 25 tonnes with Cable diverter, Hydralift
	DOHB Linear Cable Engines - 2 x DOHB 6T - Hydralift 6WP
	Transporters – 3 x DOHB 2T – Hvdralift 2 WP
TYPE OF PLOUGH	SMD - ALPHA Plough
TYPE OF ROV	1 LD Travocean ROVJet 402 (300 kW, 2500 m)
CABLE LAYING SOFTWARE	MakaiLay and WinFrog
DYNAMIC POSITIONING	ALSTOM ADP 22
TRANSIT SPEED	15 knots
POWER GENERATION	2 x 2925 kW WARTSILA + 2 x 1440 kW WARTSILA
SIDE THRUSTERS	2 x Lips 1500 kW Bow Thrusters, 2 x Lips 1500 kW Aft Thrusters
PROPULSION	2 x 5295 kW (type "12 VDS48/42AL2") - 500 / 221 rpm + 2 x controllable pitch propellers 3400 mm diameter

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# Lodbrog



### Lodbrog

#### Technical Specifications

DESCRIPTION / POSITIONING	High-speed cable maintenance ship, ideal for work in harsh conditions.
	ALDA MARTINE S.A.S.
	EUGIS DRETFUS ARMATEURS S.A.S.
LUNSTRUCTION YEAR	2002
LUNVERSION YEAR	
	143.40 m
BREADTH	23.30 m
JRAFI	7.48 m (summer draft)
JEADWEIGHT	5955 mt
ACCOMMODATION	Single cabins: 40; double cabins: 10
CABLE TANK CAPACITY	1500 tonnes / 920 m³ + 1500 tonnes / 839 m³ + 1100 tonnes / 628 m³
	2 x 350 tonnes / 184 m³ + 240 tonnes / 157 m³
REPEATER STORAGE	2 x 20
CABLE MACHINERY	Drum Cable Engine – 2 x 25 tons with Cable diverter, Hydralift 1 x DOHB 6T –
	Hydralitt 6WP + 1 X DOHB 11 - Hydralitt 1WP Transporters - 3 X DOHB 21 - Hydralitt 2 WP
IYPE OF ROV	1 LD Travocean ROVJet 401 (300 kW, 2500 m)
ABLE LAYING SOFTWARE	MakaiLay and WinFrog
JYNAMIC POSITIONING	ALSIOM ADP 22
FRANSIT SPEED	16 knots
POWER GENERATION	2 x 2925 kW WARTSILA + 2 x 1440 kW WARTSILA
SIDE THRUSTERS	2 x Lips 1500 kW Bow Thrusters, 2 x Lips 1500 kW Aft Thrusters
PROPULSION	2 x 5295 kW (type "12 VDS48/42AL2") - 500 / 221 rpm + 2 x controllable pitch propellers
	3400 mm diameter







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# **Peter Faber**









#### **Peter Faber**

#### Technical Specifications

DESCRIPTION / POSITIONING	Maintenance cable ship
OWNER	ASN DK
OPERATOR	ALDA MARINE S.A.S.
SHIP MANAGER	LOUIS DREVEUS ARMATEURS S A S
FLAG	French
	1082
CONSTRUCTION YEAR	
LENGTH OVERALL	78.38 m
BREADTH	13.60 m
DRAFT	5.01 m (summer draft)
DEADWEIGHT	2854 mt
ACCOMMODATION	Single cabins: 26; double cabins: 8
CABLE TANK CAPACITY	Cable tank: $1 \times 231 \text{ m}^3$ ; $9.10 \text{ m}$ - cable tank diameter; $4.00 \text{ m}$ - cable tank coiling depth Cable hold: $1 \times 173 \text{ m}^3$ ; $8.00 \text{ m}$ - cable hold diameter; $4.00 \text{ m}$ - cable hold coiling depth
CABLE MACHINERY	2 x Linear Cable Engines - 9 Wheel pairs + 1 Wheel pair, 1 tonne 2 x DOHB Cable winches - 4 WP port side foredeck + 3 WP starboard side foredeck
	2 Capstan Cable Engines, DCE – 1 port side + 1 starboard side, cable puil 25 tonnes
IYPE OF ROV	1 LD Travocean ROVJet 403 (300 kW, 2500 m)
CABLE LAYING SOFTWARE	MakaiLay and WinFrog
DYNAMIC POSITIONING	1 x DP ALSTOM DPS 901 Simplex Dynamic Position Control System
TRANSIT SPEED	12 knots
POWER GENERATION	2 x 562 kW + 1 x 728 kW shaft generator
THRUSTERS	1 x 725 kW Bow Thruster: 1 x 675 kW Stern Thruster
	2 REW 1050 kW each + 1 x controllable pitch propeller
FILOFULJIUN	Z DAM TOOD KW Each + T V COULIOURDIE BITCH BIODEIIEI









### lle d'Aix



### lle d'Aix

#### Technical Specifications

DESCRIPTION / POSITIONIN
OWNER
OPERATOR
SHIP MANAGER
FLAG
CONSTRUCTION YEAR
LENGTH OVERALL
BREADTH
DRAFT
DEADWEIGHT
ACCOMMODATION
CABLE TANK CAPACITY
REPEATER STORAGE
CABLE MACHINERY
TYPE OF ROV
CABLE LAYING SOFTWARE
DYNAMIC POSITIONING
TRANSIT SPEED
POWER GENERATION
SIDE THRUSTERS
PROPULSION

Maintenance cable ship LOUIS DREYFUS ARMATEURS S.A.S. ALDA MARINE Gestion Lodbrog Peter Faber S.A.S. LOUIS DREYFUS ARMATEURS S.A.S. French 1991 151.54 m 21.60 m 7.80 m (summer draft) 7892 mt Single cabins: 8; double cabins: 40; 4-crew cabins: 27; 6-crew cabins: 2 1 x 1133 m<sup>3</sup> - 1 x 497 m<sup>3</sup> - 1 x 367 m<sup>3</sup> - 2 x 58 m<sup>3</sup> 36 1 x Dowty, 21 Wheels Pairs - 2 x Drum Cable Engine (Dowty 3.5 m diam.) ROV ST206 WinFrog Kongsberg SDP 21 (Upgrade 2007) 13.5 knots 3 x Wartsila 9R32D - 3300 kW + 2 x Wartsila 6R22MD - 990 kW 2 x KaMeWa TT2400G/BMS-CP - Ø 2400 mm - 4 blades. Bow Thrusters 2 x Azimuth KaMeWa 2800/28 RON-CP - Ø 2800 mm - 4 blades, Stern Thrusters.







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# Alpha Plough



# **Alpha Plough**

#### Technical Specifications

#### GENERAL SPECIFICATION WEIGH

WEIGHT	14200 kg
LENGTH	Auxiliary share deployed and skids up – 9.90 m
WIDTH	Across stabilising wheels – 4.40 m
HEIGHT	Top of tow swivels when drawbar at 90° and steering at 0° – 4.50 m
BURIAL SYSTEM	Passive blade
CUTTING DISC	When deployed, the disc defines the inclined face of a trapezium of soil
	that is lifted to bury the cable
OPERATION	Pulled by tow wire from surface vessel. Full remote control from shipboard control console
	whilst being towed
OPERATING DEPTH	1500 m max
TOWING FORCES	50 tonnes max
BURIAL DEPTH	Up to 1100 mm
	1500 mm with the burial share extension fitted (soil conditions permitting)
REAR STABILISERS	Hydraulically adjustable rear stabilisers in wheel
SOIL TYPE	Any, with good rock ripping capability
	Soft mud capacity 5 kPa minimum
PLOUGHING SPEED	Up to 1 m/s
HYDRAULIC SYSTEM	
MOTOR	15 kW 3 Phase, 2000 V 50/60 Hz. Oil filled and pressure compensated
PUMP	Constant displacement gear pump giving 36 litres/min up to 250 bar at 60 Hz
SURVEILLANCE EQUIPMENT	The surveillance equipment comprises CCTV cameras, associated lamps, pan and tilt units
OBSTACLE AVOIDANCE SONAR	Manufactured by Simrad type Mesotech 9/1 6/5 kHz OA fan beam
	Range selectable up to 200 m
	Depth rating 2000 m
	Used with Mesotech MS 900 Sonar Processor





# SMD HD3 Plough









# **SMD Heavy Duty HD3 Plough**

#### **Technical Specifications**

#### **GENERAL SPECIFICATION AND OPERATION**

GENERAL SPECIFICATION AND O	
DIMENSIONS	10.82 m long (skids down, plough hinged, depressor down) 4.80 m high (plough hinged) 5.96 m wide (over rear stabilisers)
SUBMERGED WEIGHT OPERATION CONTROL	25 tonnes (excluding ripper and jetting package) Pulled by tow wire from surface vessel Full remote control from shipboard control cabin or from remote control console whilst being towed
STEER ANGLE BURIAL DEPTH	+/- 16° 2.30 m trench depth at zero share pitch (soil dependent) 3.00 m achievable in soft soils with plough pitched aft Optional interchangeable share 1.5 m available
OPERATING DEPTH	A forward mounted Rock footh can cut the trench in rock usually with a layer of soli above it 1500 m maximum
REPEATER BURIAL	Repeater burial depth 50-90% of plough burial depth, dependent on soil conditions
	Any, within finits of pull force (130 tonnes) 5 kPa minimum
PLOUGHING SPEED	Recommended maximum 2 knots depending on seabed conditions
HYDRAULIC SYSTEM	RESERVOIR: Flexible pressure compensated, 100 litres working capacity SYSTEM HYDRAULIC OIL: Houghton Vaughan Hydrodrive HPE 22
CYLINDERS	Heavy duty marine type with welded swivel eyes
SURVEILLANCE EQUIPMENT	The surveillance equipment comprises CCTV cameras, associated lamps, pan and tilt units CAMERAS: 3 x SIT
	LAMPS: 5 x 150 W 24 V incandescent SONAR: Mesotech 1000 digital sonar head (range up to 100 m) HYDROPHONE: A hydrophone is provided with an integral pre-amplifier ACOUSTIC POSITIONING: Provision is made for responder/ transponder unit





# SMD MD3 Plough









# SMD MD3 Plough

#### Technical Specifications

LENGTH WIDTH HEIGHT BURIAL SYSTEM OPERATION

OPERATING DEPTH TOWING FORCES BURIAL DEPTH

REAR STABILISERS SOIL TYPE PLOUGHING SPEED HYDRAULIC SYSTEM

SURVEILLANCE EQUIPMENT OBSTACLE AVOIDANCE SONA

#### GENERAL SPECIFICATION AND OPERATION WEIGHT 2250

	LIAHON	
	22500 kg (in air)	
	9.50 m long (skids and auxiliary share down)	
	5.60 m	
	5.00 m high (skids and drawbar fully down)	i n
	Parallel sided blade – optional disc trenching system	
	Pulled by tow wire from surface vessel	•
	Full remote control from shipboard control console whilst being towed	
	2000 m maximum	
	10-60t	
	Depths of 2.0 m to 2.2 m are achieved by plough sinkage until rear stabilisers reach fully up posi	tion
	Depth is increased from 2.2 m to 3.0 m by rotating the share hinge position with rear stabilisers.	fully up
	Hydraulically adjustable rear stabilisers	long op
	Any, with good rock ripping capability. Soft mud capacity 5 kPa minimum	
	Up to 1 m/s	
	RESERVOIR: Elexible pressure compensated, 100 litres working capacity	
	HYDRAULIC OIL: Houghton Vaughan Hydrodrive HPE 118	
	CYLINDERS: Heavy duty marine type with welded swivel eyes	
	The surveillance equipment comprises CCTV cameras associated lamps, pap and tilt units	
R	A scanning sonar head is mounted at the front of the plough A Mesotech 9000 or	
	equivalent sonar system can be installed	









### **ROVJet 400 & Dynacon LARS**



### **ROVJet 400 & Dynacon LARS**

#### Technical Specifications

LARS	Dynacon Model 1015 Telescoping horizontal luffing, lifting umbilical SWL 13.5 tonnes, max operating sea state: 6
ROV	
CONFIGURATION TOTAL POWER MAXIMUM DEPTH RATING	Vehicle free-swimming or on tracks 300 kW (400 hp) 2500 m
DIMENSIONS (APPROX.) WEIGHT IN AIR (APPROX.)	Length: 5.00 m; Width (on tracks): 3.40 m; Height: 2.00 m 10 tonnes with tracks, 9 tonnes without tracks
HP JETTING SYSTEM	1 x 93 kW 2 pole 3.3 kV electro-jetting units for HP Jetting 1 x 125 HP Flowserve Type QN102-2A HP jetting pump Nominal Jet Pressure: 7 bar (300 m3/b)
LP JETTING SYSTEM	1 x 93 kW 2 pole 3.3 kV electro-jetting units for LP Jetting 1 x 125 HP Flowserve Type QN122-1A LP jetting pump
JETTING TOOLS	Nominal Jet Pressure: 3 bar (550 m3/n) 1 x Main Jetting Tool HP & LP Flow for Depth Burial
	Depth control: 0-2000 mm (0-3000 mm on Lodbrog) with main swords
	1 m and 2 m swords option (3 m sword option on Lodbrog) Transducers: Tool Depth (transducer fitted on cylinder)
	Depressor height, Water pressure, Cable Detection 1 x Forward Jetting Tool
	Depth control: 0-400 mm
SURVEILLANCE EQUIPMENT	2 x Typhoon 22:1 Colour Zoom, 2 x CCD monochrome, 1 x Tornado Low Light Camera
PAN & TILTS OA SONAR	2 x PT10-FB-120V-OIL-AL with feedback Tritech Super Seeking DFS
ECHO SOUNDER CABLE TRACKER	Tritech PA500:6-S. Range: 50 m TSS 440/350 Dual track on deployment frame
LABLE TUULS PALKAUE	(special for cutting application), Webtool HCV100, LD Travocean Cable Clamp









#### **ROVJet 400 and Heila LARS**



#### **ROVJet 400 & Heila LARS**

#### Technical Specifications

_ARS	HEILA HLRM 240/2S crane SWL 7.1 tonnes, max operating sea state : 4
CONFIGURATION	venicle free-swimming or on tracks 300 kW (400 hp)
MAXIMUM DEPTH RATING	2500 m
DIMENSIONS (APPROX.) WEIGHT IN AIR (APPROX.)	Length: 5.00 m; Width (on tracks): 3.40 m; Height: 2.00 m 10 tonnes with tracks, 9 tonnes without tracks
HP JETTING SYSTEM	1 x 93 kW 2 pole 3.3 kV electro-jetting units for HP Jetting 1 x 125 HP Flowserve Type QN102-2A HP jetting pump
	Nominal Jet Pressure: 7 bar (300 m3/h)
_P JETTING SYSTEM	1 x 93 kW 2 pole 3.3 kV electro-jetting units for LP Jetting 1 x 125 HP Flowserve Type QN122-1A LP jetting pump
ΙΕΤΤΙΝΟ ΤΟΟΙ S	1 x Main let Tool
	HP & LP Flow for Depth Burial
	Depth control: 0-2000 mm (0-3000 mm on Lodbrog) with
	main swords
	1 m and 2 m swords option (3 m sword option on Lodbrog) Transducers: Tool Depth (transducer fitted on cylinder)
	Depressor height, Water pressure, Cable Detection
	I X FORWARD JELLING TOOT HP Flow for Surface Trenching
SURVEILLANCE EQUIPMENT	2 x Typhoon 22:1 Colour Zoom, 2 x CCD monochrome, 1 x Tornado Low Light Camera
PAN & TILTS	2 x PT10-FB-120V-OIL-AL with feedback
DA SONAR	Tritech Super Seeking DFS
ECHO SOUNDER	Tritech PA500:6-S Range: 50 m
CABLE TRACKER	TSS 440/350 Dual track on deployment frame
LABLE TOULS PACKAGE	1 X Schilling Urion /P, 1 X LD Travocean 3R (special for sutting application)
	Webtool HCV100, LD Travocean Cable Clamp





ROVS

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# V8 Sii ROV









# V8 Sii ROV

#### **Technical Specifications**

#### CONFIGURATION

POWER DEPTH RATING DIMENSIONS (APPROX.) WEIGHT IN AIR (APPROX.) MANIPULATORS CAMERA AND LIGHT

SONAR POSITIONING TRANSMISSION LIGHT UMBILICAL 360° freedom of movement in three dimensions, 8 vectored thrusters Extremely advanced control system. 5 kW 500 m Length: 780 mm; Width: 670 mm; Height: 470 mm 60kg 1 function 1 x wide angle Bowtech Surveyor colour zoom 1 x small camera with light back end Tritek Micron USBL 319 micro beacon Fibre-Optic, NTSC or PAL Bowtech LED-3200 Length 400 m fibre-optic on winch

Self-contained 20ft container for L&R during DP operations. Compass, auto depth, auto heading, pitch & roll, depth sensor. Laptop with software for sonar and recording, HDD recorder with external screen.









# ST206 ROV



#### ST206 ROV

#### Technical Specifications

CONFIGURATION	Vehicle free-swimming or on tracks	
TOTAL POWER	150 kW	
MAXIMUM DEPTH RATING	2500 m	
DIMENSIONS (APPROX.)	Length: 3.30 m; Width (on tracks): 3.94 m; Height: 2.92 m	
WEIGHT IN AIR (APPROX.)	7 tonnes with tracks, 6 tonnes without tracks	
JETTING SYSTEM	Two Fybroc high pressure water pumps are directly coupled	
	to and driven by the hydraulic motors. They deliver 700 gpm,	
	120 psi at 3500 rpm. Power sharing Hydraulic system under	
	operator control.	¢.
JETTING TOOLS	Perry Tritech Advanced Cable Burial tool mounted in front	
	of ROV, optimized for 0 to 30 kPa. Burial tools for different	
	seabed condition can be installed.	
	Interchangeable Jetting configurations with U.7 m and	
	1.5 m legs providing burial up to 1.5 meters.	
SURVEILLANCE EQUIPMENT	I X SIIIIIdu I3241 SII (dilleid, 2 x Simrad 1300T CCD calaur camaras (zaam)	
	5 X Sillidu ISOOT CCD tuluur talileids (20011), 1 x Simrad 1202T black & white camera	
	2 x 14-100 mini CCD colour comeros	
	all fitted in Titanium bousings	ጠ
PAN & THITS	3 x Perry Tritech PT2712 units	
TAN & HEIS	1 x Perry Tritech Tilt unit	
OA SONAR	Mesotech 900D with 1071 upgraded head	П
DEPTH SENSOR:	High Accuracy Digiguartz Paroscientific pressure transducer	
CABLE TRACKER	TSS 440/350 Dual track. Armoured cable range up to 1.2 m	
CABLE TOOLS PACKAGE	2 x Schilling Orion 7RE. 7 functions	
	Webbtool HCV-100 for cutting.	
	Capacity up to 108 mm double row armoured	뒿
	Slingsby Engineering TA-0017 up to 100 mm cable	7
	diameter for gripping.	







# Cut and hold grapnel









#### **Deep Sea Cut and Hold Grapnel**

2300 mm

1000 mm

Capable of recovering a cable from depths of up to 9000 m. Designed jointly by Alcatel-Lucent and Ocean Cable Technologies.

The use of a cut and hold grapnel can significantly enhance marine repair operations when locating and recovering the first cable end, particularly in deeper waters on lightweight cable variants. Use of this tool will save on average 18 hours of operational time compared to using traditional cut and hold methods.

The cut and hold grapnel has been designed to locate, cut and recover all LW and LWP cables currently in use. Capable of holding the cable up to and beyond its NTTS value, regardless of size or strength, it ensures the cable is retrieved effectively to the surface and the risk of the cable end being lost during recovery is minimal.

The Ocean Cable Technologies cut and hold grapnel utilises the energy derived from the vessel's tow cable as the power source. This purely mechanical design with no electrical or hydraulic parts means that the tool is not only energy efficient but also highly reliable.

#### Technical Specifications

#### DIMENSIONS

LENGTH WIDTH HEIGHT (excluding tine) DEPTH (including tine) CABLES QUALIFIED OR UNDER QUALIFICATION

GRIPPING DEVICE TEST CRITERIA

#### 360 mm 880 mm ASN OALC4 LW, Pirelli 18 mm LWP ASN OALC4 LWP, OCC SC300 LWP STC NL, OCC SC100 LWP Tyco SL 17 mm, Siemens Minisub LW Tensile Test to NTTS 1 hour Tensile Test to NTTS through 90° 1 hour Tensile Test to Failure Tensile Test to Failure through 90° 12 hour at NTTS Full depth recovery test All tests repeated in salt water, sand, mud, gravel, grease and oil

#### PHYSICAL PROPERTIES

MAXIMUM TENSILE STRENGTH ACTIVATION LOAD BREAK OUT LOAD WEIGHT 15 tonnes Variable 0.3-2.0 tonne 10 tonne 2 tonne







# Jointing and services



# **Jointing and Services**

The Jointing and Services team (JAS) located at the Alcatel-Lucent Submarine Network cable production site in Calais, France is responsible for the organisation of jointing activities on board Alcatel-Lucent installation and maintenance ships and testing during system repair operations.

#### Cable Jointing

Cable jointing is a specialised activity that requires a high level of skill and experience in the use of jointing tools and equipment. All Alcatel-Lucent jointing personnel are fully qualified to make optical fibre cable joints and undergo regular refresh training in the Alcatel-Lucent Jointer Training School to ensure their skill levels are maintained to the agreed standard. Jointers are trained to use current and legacy jointing technologies and equipment to maintain their skills and qualifications at the highest level. A complete set of jointing equipment including contingency spares is held on board all Alcatel-Lucent vessels and is regularly checked and maintained to ensure optimum reliability and availability at all times.

The Jointing and Services team also manages stocking and replenishing of jointing kits with the main focus on ensuring that the right type and quantity of kits are in the right place at the right time for any incident that requires a cable joint.

Specifically developed for the maintenance of optical fibre cable systems, Universal Jointing (UJ) technology is the main jointing technology deployed on board Alcatel-Lucent vessels allowing joints to be made between cables from different manufacturers. Alcatel-Lucent installation ships are also equipped to use ASN jointing technology, which is consistent with the jointing techniques used in the factory during the manufacture of Alcatel-Lucent cables.

#### Testing

For repair operations, testing is a key stage in the process of fault location and to ensure that the cable is safe for jointing. On each Alcatel-Lucent maintenance ship there is a test engineer, who is responsible for the testing and validation of submarine cables and associated submerged equipment such as repeaters, equalisers and branching units. The test engineer directs and controls inspection and testing, interprets, evaluates and documents test results and provides technical support to customers, if required. The test engineer is also responsible for the operation and maintenance of all electrical and optical testing equipment on board the vessel.

















# **Expertise**

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